

FANUC Robot R-2000iC



Features

The FANUC Robot R-2000iC is an intelligent robot based on FANUC's years of experience and renowned technology. This high performance intelligent robot with outstanding reliability and cost performance will support your needs in various applications, such as spot welding, material handling and assembly.

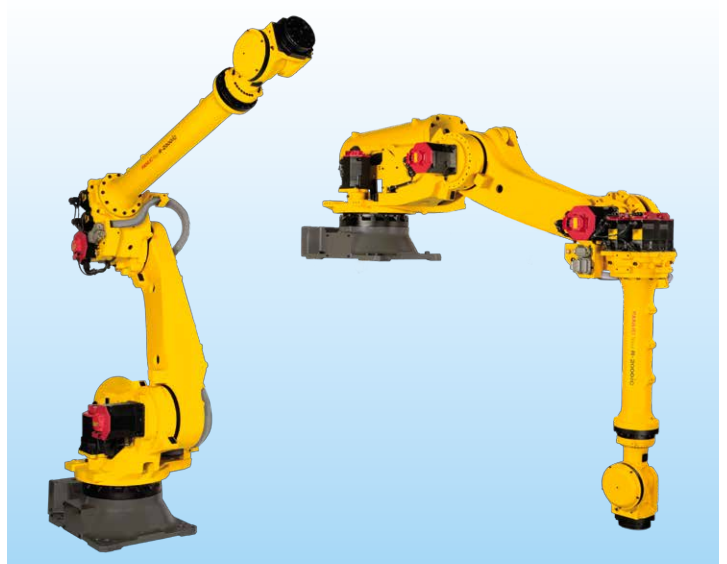
- Weight reduction of the mechanical unit and compact robot
- The rigid yet lightweight arm and the advanced motion control technology achieve significantly improved motion performance, allowing for higher productivity.
- Extensive options are available for various processes, including the spot welding solution arm.
- The R-30iB/R-30iB Plus controller provides energy and floor space savings with its energy regeneration option and compact cabinet.
- Available with the various intelligent features such as the Learning Robot, Bin Picking, Force Sensing and Visual Line Tracking.

Application Example



High Speed Spot Welding

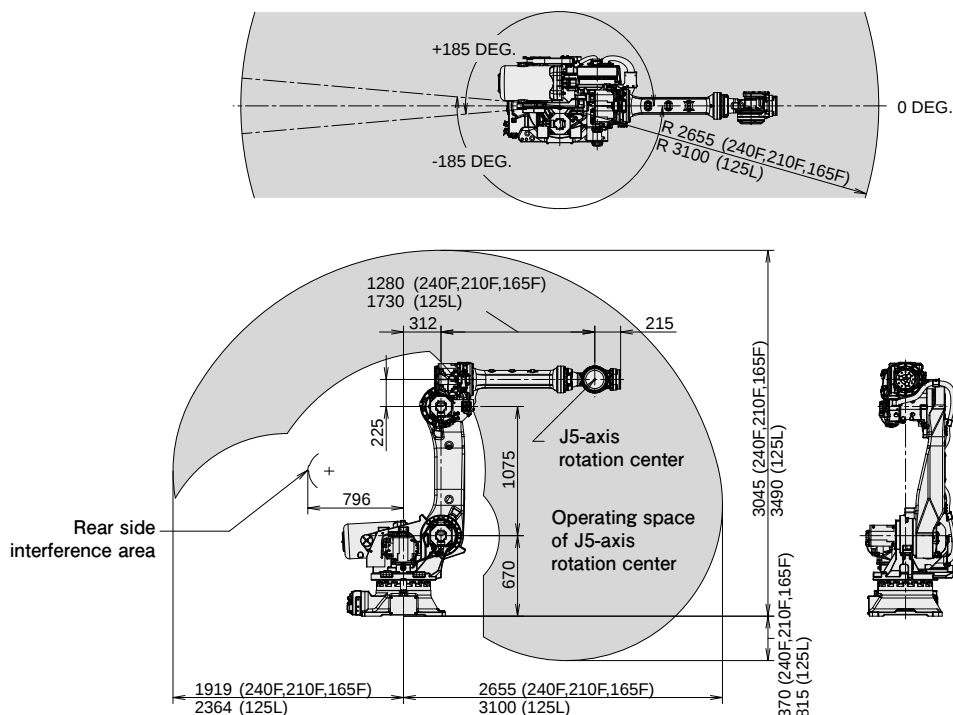
Lineup



Long Reach/Rack Mount

Operating space

R-2000iC/240F,/210F,/165F,/125L



Specifications

Model		R-2000iC/240F	R-2000iC/210F	R-2000iC/165F	R-2000iC/125L
Type		Articulated Type			
Controlled axes		6 axes (J1, J2, J3, J4, J5, J6)			
Reach		2655 mm			3100 mm
Installation		Floor			
Motion range (Maximum speed) Note 1)	J1 axis rotation	370°(115°/s) 6.46 rad (2.01 rad/s)	370°(120°/s) 6.46 rad (2.09 rad/s)	370°(130°/s) 6.46 rad (2.27 rad/s)	
	J2 axis rotation	136°(90°/s) 2.37 rad (1.57 rad/s)	136°(105°/s) 2.37 rad (1.83 rad/s)	136°(115°/s) 2.37 rad (2.01 rad/s)	
	J3 axis rotation	312°(105°/s) 5.45 rad (1.83 rad/s)	312°(110°/s) 5.45 rad (1.92 rad/s)	312°(125°/s) 5.45 rad (2.18 rad/s)	301°(125°/s) 5.25 rad (2.18 rad/s)
	J4 axis wrist rotation	720°(130°/s) 12.57 rad (2.27 rad/s)	720°(140°/s) 12.57 rad (2.44 rad/s)	720°(180°/s) 12.57 rad (3.14 rad/s)	
	J5 axis wrist swing	250°(130°/s) 4.36 rad (2.27 rad/s)	250°(140°/s) 4.36 rad (2.44 rad/s)	250°(180°/s) 4.36 rad (3.14 rad/s)	
	J6 axis wrist rotation	720°(210°/s) 12.57 rad (3.67 rad/s)	720°(220°/s) 12.57 rad (3.84 rad/s)	720°(260°/s) 12.57 rad (4.54 rad/s)	
	J6 axis wrist rotation	12.57 rad (3.67 rad/s)	12.57 rad (3.84 rad/s)	12.57 rad (4.54 rad/s)	
Max. load capacity at wrist		240 kg	210 kg	165 kg	125 kg
Max. load capacity at J2 base		550 kg	550 kg	550 kg	550 kg
Max. load capacity on J3 arm		25 kg (A) 50 kg (B)	25 kg (A) 50 kg (B)	25 kg (A) 50 kg (B)	25 kg (A) 40 kg (B)
Max. load capacity on J3 casing		(A) + (B) ≤ 50 kg	(A) + (B) ≤ 50 kg	(A) + (B) ≤ 50 kg	(A) + (B) ≤ 40 kg
Allowable load moment at wrist	J4 axis	1400 N·m 143 kgf·m	1360 N·m 139 kgf·m	940 N·m 96 kgf·m	710 N·m 72 kgf·m
	J5 axis	1400 N·m 143 kgf·m	1360 N·m 139 kgf·m	940 N·m 96 kgf·m	710 N·m 72 kgf·m
	J6 axis	800 N·m 82 kgf·m	735 N·m 75 kgf·m	490 N·m 50 kgf·m	355 N·m 36 kgf·m
Allowable load inertia at wrist	J4 axis	250 kg·m² 2551 kgf·cm·s²	147 kg·m² 1500 kgf·cm·s²	89 kg·m² 908 kgf·cm·s²	72 kg·m² 735 kgf·cm·s²
	J5 axis	250 kg·m² 2551 kgf·cm·s²	147 kg·m² 1500 kgf·cm·s²	89 kg·m² 908 kgf·cm·s²	72 kg·m² 735 kgf·cm·s²
	J6 axis	200 kg·m² 2041 kgf·cm·s²	82 kg·m² 837 kgf·cm·s²	46 kg·m² 469 kgf·cm·s²	40 kg·m² 408 kgf·cm·s²
Drive method		Electric servo drive by AC servo motor			
Repeatability Note 2)		± 0.05 mm			
Mass Note 3)		1090 kg	1090 kg	1090 kg	1115 kg
Installation environment		Ambient temperature : 0 to 45°C Ambient humidity : Normally 75%RH or less (No dew, nor frost allowed) Short term Max. 95%RH or less (within one month) Vibration acceleration : 4.9m/s² (0.5G) or less			

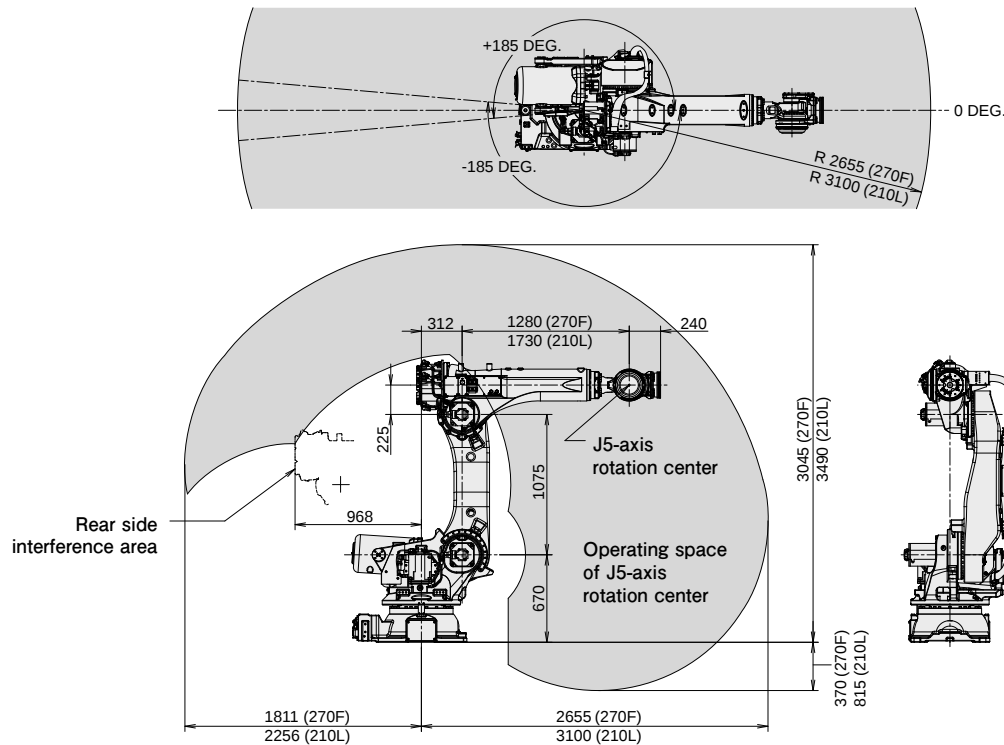
Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Compliant with ISO 9283.

Note 3) Without controller.

Operating space

R-2000iC/270F,/210L



Specifications

Model		R-2000iC/270F		R-2000iC/210L	
Type		Articulated Type			
Controlled axes		6 axes (J1, J2, J3, J4, J5, J6)			
Reach		2655 mm		3100 mm	
Installation		Floor			
Motion range (Maximum speed) Note 1)	J1 axis rotation	370°(105°/s) 6.46 rad (1.83 rad/s)			
	J2 axis rotation	136°(90°/s) 2.37 rad (1.57 rad/s)			
	J3 axis rotation	312°(85°/s)	5.45 rad (1.48 rad/s)	301°(85°/s)	5.25 rad (1.48 rad/s)
	J4 axis wrist rotation	720°(120°/s) 12.57 rad (2.09 rad/s)			
	J5 axis wrist swing	250°(120°/s) 4.36 rad (2.09 rad/s)			
	J6 axis wrist rotation	720°(200°/s) 12.57 rad (3.49 rad/s)			
Max. load capacity at wrist		270 kg		210 kg	
Max. load capacity at J2 base		550 kg		550 kg	
Max. load capacity on J3 arm		40 kg (A)	(A)×5/4+(B) ≤ 50 kg	20 kg (A)	(A)×5/2+(B) ≤ 50 kg
Max. load capacity on J3 casing		50 kg (B)		50 kg (B)	
Allowable load moment at wrist	J4 axis	1730 N·m 177 kgf·m		1700 N·m 173 kgf·m	
	J5 axis	1730 N·m 177 kgf·m		1700 N·m 173 kgf·m	
	J6 axis	900 N·m 92 kgf·m		900 N·m 92 kgf·m	
Allowable load inertia at wrist	J4 axis	320 kg·m ²	3265 kgf·cm·s ²	320 kg·m ²	3265 kgf·cm·s ²
	J5 axis	320 kg·m ²	3265 kgf·cm·s ²	320 kg·m ²	3265 kgf·cm·s ²
	J6 axis	230 kg·m ²	2347 kgf·cm·s ²	230 kg·m ²	2347 kgf·cm·s ²
Drive method		Electric servo drive by AC servo motor			
Repeatability Note 2)		± 0.05 mm			
Mass Note 3)		1320 kg		1350 kg	
Installation environment		Ambient temperature : 0 to 45°C Ambient humidity : Normally 75%RH or less (No dew, nor frost allowed) Short term Max. 95 %RH or less (within one month) Vibration acceleration : 4.9 m/s ² (0.5G) or less			

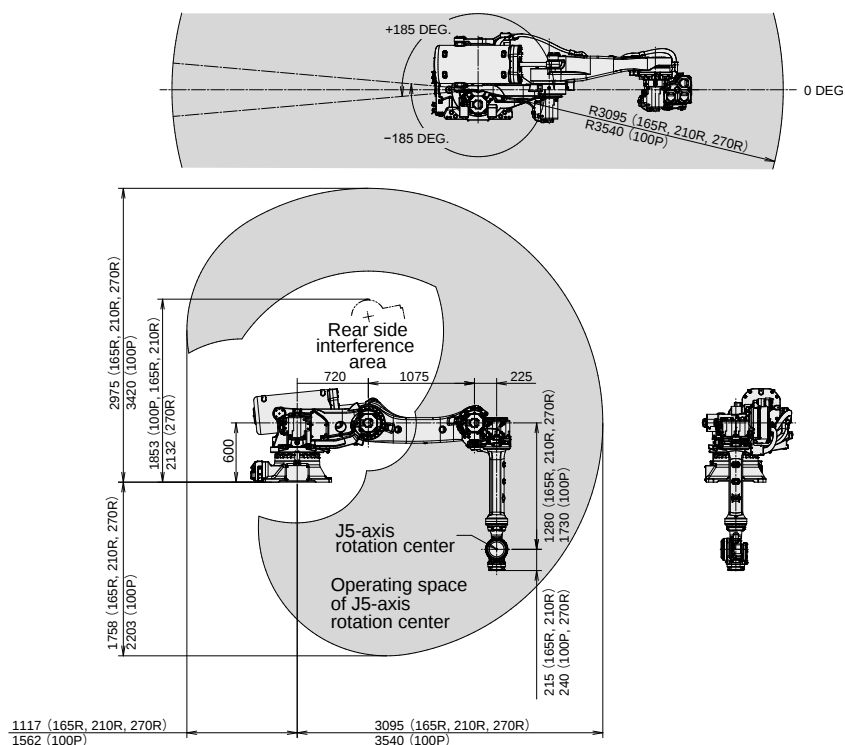
Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Compliant with ISO 9283.

Note 3) Without controller.

Operating space

R-2000iC/270R,/210R,/165R,/100P



Specifications

Model		R-2000iC/270R	R-2000iC/210R	R-2000iC/165R	R-2000iC/100P
Type		Articulated Type			
Controlled axes		6 axes (J1, J2, J3, J4, J5, J6)			
Reach		3095 mm			3540 mm
Installation		Rack mount			
Motion range (Maximum speed) Note 1)	J1 axis rotation	370°(105°/s) 6.46 rad (1.83 rad/s)	370°(105°/s) 6.46 rad (1.83 rad/s)	370°(115°/s) 6.46 rad (2.01 rad/s)	370°(120°/s) 6.46 rad (2.09 rad/s)
	J2 axis rotation	200°(85°/s) 3.49 rad (1.48 rad/s)	200°(100°/s) 3.49 rad (1.75 rad/s)	200°(110°/s) 3.49 rad (1.92 rad/s)	200°(100°/s) 3.49 rad (1.75 rad/s)
	J3 axis rotation	375°(85°/s) 6.54 rad (1.48 rad/s)	375°(110°/s) 6.54 rad (1.92 rad/s)	375°(125°/s) 6.54 rad (2.18 rad/s)	375°(115°/s) 6.54 rad (2.01 rad/s)
	J4 axis wrist rotation	720°(120°/s) 12.57 rad (2.09 rad/s)	720°(140°/s) 12.57 rad (2.44 rad/s)	720°(180°/s) 12.57 rad (3.14 rad/s)	720°(140°/s) 12.57 rad (2.44 rad/s)
	J5 axis wrist swing	250°(120°/s) 4.36 rad (2.09 rad/s)	250°(140°/s) 4.36 rad (2.44 rad/s)	250°(180°/s) 4.36 rad (3.14 rad/s)	250°(140°/s) 4.36 rad (2.44 rad/s)
	J6 axis wrist rotation	720°(200°/s) 12.57 rad (3.49 rad/s)	720°(220°/s) 12.57 rad (3.84 rad/s)	720°(260°/s) 12.57 rad (4.54 rad/s)	720°(210°/s) 12.57 rad (3.66 rad/s)
	Max. load capacity at wrist	270 kg	210 kg	165 kg	100 kg
Max. load capacity at J2 base		550 kg	550 kg	550 kg	550 kg
Max. load capacity on J3 arm		30 kg (A) (A)×4/3+(B) ≤ 40 kg (B)	30 kg (A) (A)×4/3+(B) ≤ 40 kg (B)	25 kg (A) (A) + (B) ≤ 50 kg (B)	25 kg (A) (A)×2+(B) ≤ 50kg (B)
Allowable load moment at wrist		J4 axis 1730 N·m 177 kgf·m J5 axis 1730 N·m 177 kgf·m J6 axis 900 N·m 92 kgf·m	J4 axis 1360 N·m 139 kgf·m J5 axis 1360 N·m 139 kgf·m J6 axis 735 N·m 75 kgf·m	J4 axis 940 N·m 96 kgf·m J5 axis 940 N·m 96 kgf·m J6 axis 490 N·m 50 kgf·m	J4 axis 1000 N·m 102 kgf·m J5 axis 1000 N·m 102 kgf·m J6 axis 706 N·m 72 kgf·m
Allowable load inertia at wrist	J4 axis	320 kg·m ² 3265 kgf·cm·s ²	147 kg·m ² 1500 kgf·cm·s ²	89 kg·m ² 908 kgf·cm·s ²	227 kg·m ² 2316 kgf·cm·s ²
	J5 axis	320 kg·m ² 3265 kgf·cm·s ²	147 kg·m ² 1500 kgf·cm·s ²	89 kg·m ² 908 kgf·cm·s ²	227 kg·m ² 2316 kgf·cm·s ²
	J6 axis	230 kg·m ² 2347 kgf·cm·s ²	82 kg·m ² 837 kgf·cm·s ²	46 kg·m ² 469 kgf·cm·s ²	196 kg·m ² 2000 kgf·cm·s ²
Drive method		Electric servo drive by AC servo motor			
Repeatability Note 2)		± 0.05 mm			
Mass Note 3)		1590 kg	1370 kg	1370 kg	1470 kg
Installation environment		Ambient temperature : 0 to 45°C Ambient humidity : Normally 75 %RH or less (No dew, nor frost allowed) Short term Max. 95 %RH or less (within one month) Vibration acceleration : 4.9 m/s ² (0.5G) or less			

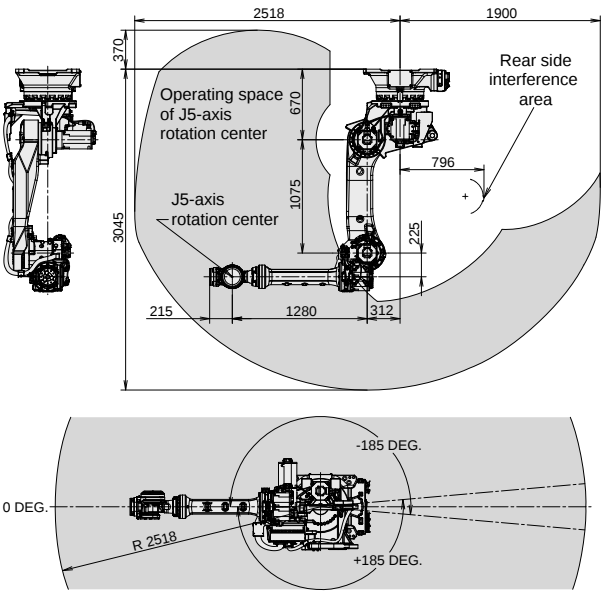
Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Compliant with ISO 9283.

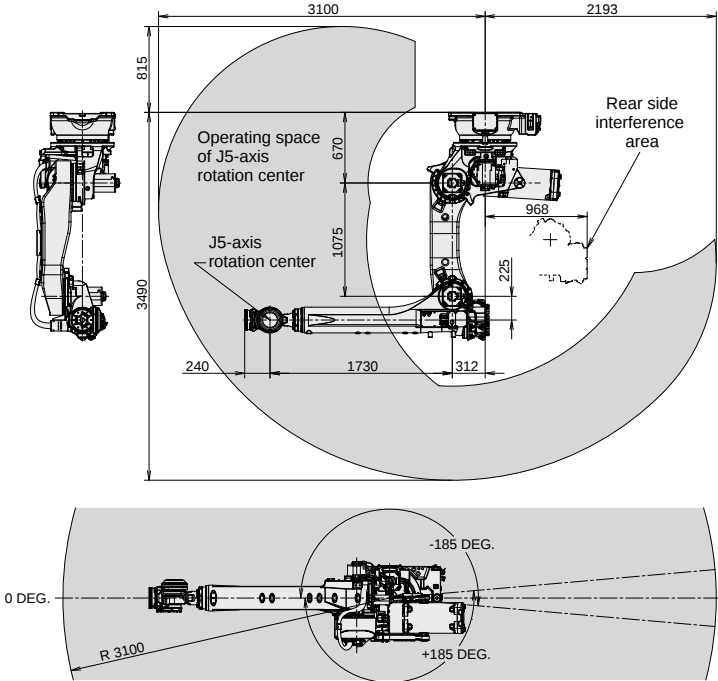
Note 3) Without controller.

Operating space

R-2000iC/220U



R-2000iC/190U



Specifications

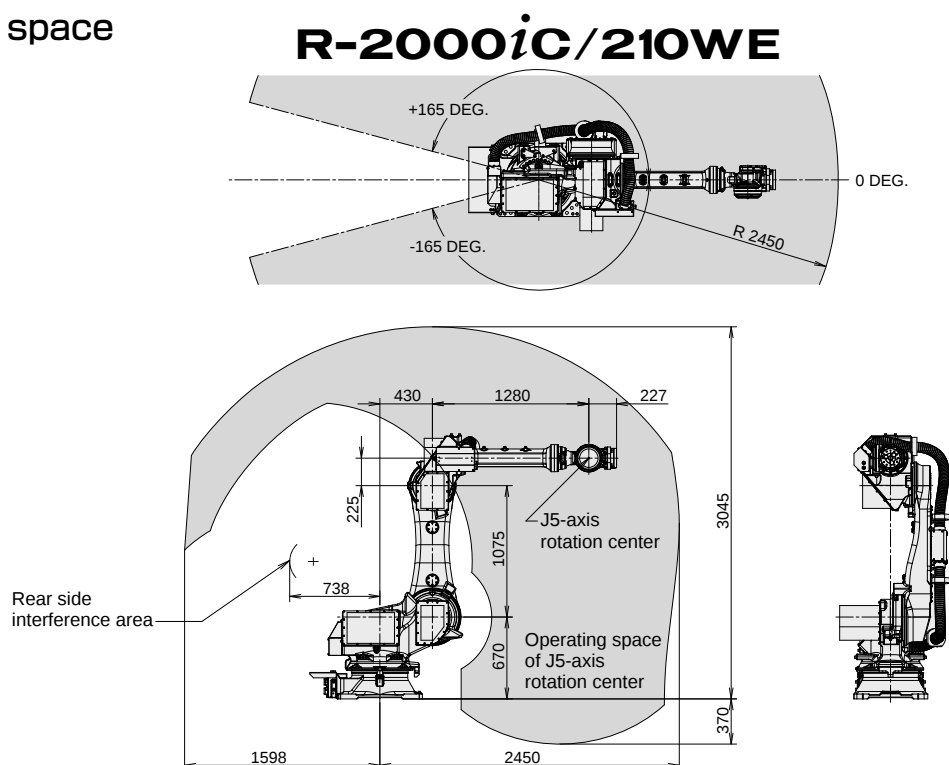
Model		R-2000iC/220U		R-2000iC/190U	
Type		Articulated Type			
Controlled axes		6 axes (J1, J2, J3, J4, J5, J6)			
Reach		2518 mm		3100 mm	
Installation		Upside-down			
Motion range (Maximum speed) Note 1)	J1 axis rotation	370°(120°/s)	6.46 rad (2.09 rad/s)	370°(105°/s)	6.46 rad (1.83 rad/s)
	J2 axis rotation	136°(85°/s)	2.37 rad (1.48 rad/s)	136°(85°/s)	2.37 rad (1.48 rad/s)
	J3 axis rotation	312°(110°/s)	5.45 rad (1.92 rad/s)	301°(85°/s)	5.25 rad (1.48 rad/s)
	J4 axis wrist rotation	720°(140°/s)	12.57 rad (2.44 rad/s)	720°(120°/s)	12.57 rad (2.09 rad/s)
	J5 axis wrist swing	250°(140°/s)	4.36 rad (2.44 rad/s)	250°(120°/s)	4.36 rad (2.09 rad/s)
	J6 axis wrist rotation	720°(220°/s)	12.57 rad (3.84 rad/s)	720°(200°/s)	12.57 rad (3.49 rad/s)
Max. load capacity at wrist		220 kg		190 kg	
Max. load capacity at J2 base		-			
Max. load capacity on J3 arm		25 kg (A)	(A)×6/5 + (B) ≤ 30kg	20 kg (A)	(A)×5/2 + (B) ≤ 50kg
Max. load capacity on J3 casing		30 kg (B)		50 kg (B)	
Allowable load moment at wrist	J4 axis	1360 N·m	139 kgf·m	1700 N·m	173 kgf·m
	J5 axis	1360 N·m	139 kgf·m	1700 N·m	173 kgf·m
	J6 axis	735 N·m	75 kgf·m	900 N·m	92 kgf·m
Allowable load inertia at wrist	J4 axis	147 kg·m ²	1500 kgf·cm·s ²	320 kg·m ²	3265 kgf·cm·s ²
	J5 axis	147 kg·m ²	1500 kgf·cm·s ²	320 kg·m ²	3265 kgf·cm·s ²
	J6 axis	82 kg·m ²	837 kgf·cm·s ²	230 kg·m ²	2347 kgf·cm·s ²
Drive method		Electric servo drive by AC servo motor			
Repeatability Note 2)		± 0.05 mm			
Mass Note 3)		1020 kg		1400 kg	
Installation environment		Ambient temperature : 0 to 45°C Ambient humidity : Normally 75 %RH or less (No dew, nor frost allowed) Short term Max. 95 %RH or less (within one month) Vibration acceleration : 4.9 m/s ² (0.5G) or less			

Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Compliant with ISO 9283.

Note 3) Without controller.

Operating space



Specifications

Model		R-2000iC/210WE	
Type		Articulated Type	
Controlled axes		6 axes (J1, J2, J3, J4, J5, J6)	
Reach		2450 mm	
Installation		Floor	
Motion range (Maximum speed) Note 1)	J1 axis rotation	330°(95°/s)	5.76 rad (1.66 rad/s)
	J2 axis rotation	141°(85°/s)	2.46 rad (1.48 rad/s)
	J3 axis rotation	318°(95°/s)	5.55 rad (1.66 rad/s)
	J4 axis wrist rotation	720°(120°/s)	12.57 rad (2.09 rad/s)
	J5 axis wrist swing	250°(120°/s)	4.36 rad (2.09 rad/s)
	J6 axis wrist rotation	720°(190°/s)	12.57 rad (3.32 rad/s)
Max. load capacity at wrist		210 kg	
Max. load capacity at J2 base		550 kg	
Max. load capacity on J3 arm		-	
Max. load capacity on J3 casing		10 kg	
Allowable load moment at wrist	J4 axis	1333 N·m	136 kgf·m
	J5 axis	1333 N·m	136 kgf·m
	J6 axis	706 N·m	72 kgf·m
Allowable load inertia at wrist	J4 axis	141.1 kg·m ²	1440 kgf·cm·s ²
	J5 axis	141.1 kg·m ²	1440 kgf·cm·s ²
	J6 axis	78.4 kg·m ²	800 kgf·cm·s ²
Drive method		Electric servo drive by AC servo motor	
Repeatability Note 2)		± 0.1 mm	
Mass Note 3)		1180 kg	
Installation environment Note 4)		Ambient temperature : 0 to 55°C(Robot), 0 to 45°C(Controller) Washing solution temperature : Up to 60°C Vibration acceleration : 4.9 m/s ² (0.5G) or less	

Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Compliant with ISO 9283.

Note 3) Without controller.

Note 4) Air purge is required.

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